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They are all linear. To see that rotation is linear, use trigonometry to deduce that if  $p =$ , then  $f(p) = u =$ , where  $x^2 + u^2 = (\cos \theta)x - (\sin \theta)u$   $x^2 + u^2 = (\sin \theta)x + (\cos \theta)u$ .  $f$  is linear because this a special case of Example 3.3.2. To see that reflection is linear, write  $p =$  and  $f(p) =$ .

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Very good question: I get the fact that this is not a pure "math" question but given the audience, posting the question here is a good way to potentially get an answer. Thanks a lot to Prof Boyd and Prof Vandenberghe to make their high quality book free online. However for the ones (like me) who (try to) learn the subject by themselves and not have time/money to go to Stanford ...

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(From Applied Linear Algebra, by James W. Demmel.) Let  $A$ ,  $B$  and  $C$  be matrices with dimensions such that the product  $ATCB^T$  is defined. Let  $x$  be the set of matrices  $X$  minimizing  $\|AXB - C\|_F$ , and let  $X$ , be the unique member of  $x$  with minimum  $\|X\|_F$ . Show that  $X = ACB^T$ . Hint: Use the SVDs of  $A$  and  $B$ .

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